

euRathlon 2014

29th September - 3rd October 2014,

La Spezia, Italy

Team Information Form

Team Details

Team Name:

Robdos

Institution/Company:

ETSIN-UPM

Robdos

Logo (attach or insert here):



Escuela Técnica Superior de
Ingenieros Navales

ROBDOS

Website:

<http://www.robdos.com>

<http://www.upm.es/ETSINavales>

Home location of team:

Madrid

Name of team leader:

Hugo Ramos Castro

Picture of team leader (attach or insert here):



When was the team established (year): 2013

Team Description (including names of the team members):

Hugo Ramos Castro
Pierre Soulard
Álvaro Villalba Rodríguez
Gregorio Juliana Quirós

Team Sponsors (if any):

Contact Details

Team E-mail: hugo.ramos@robdos.es

Institution/Company: Robdos

Address: Calle Belen nº14, 1º piso
28004 Madrid
España

Telephone: +34691309457

Fax:

Other information (will not be published)

Proof of citizenship (please attach a scan): a copy of the team leader's ID/passport will do.

Brief CVs of the team members (please attach a pdf)

Send form to: ferri@cmre.nato.int

NOTE: All the information in this form, except the proof of citizenship and CVs, will be published on the website. If you wish to keep some information private, please let us know.

SCENARIO SELECTION AND VEHICLE(S) SPECIFICATION (Complete one table per vehicle)

SCENARIO SELECTION PER VEHICLE								
Vehicle name		Team name		Team leader				
<i>Vehicle picture (attach or insert here)</i>	Age of current vehicle	Will it participate in SAUCE'14? If so, specify budget.	EURATHLON 2014: Selection of scenarios (please check all scenarios you wish to enter with this vehicle)					
			yes	Long range autonomous underwater navigation				
			yes	Environmental survey of the accident area (mapping)				
			yes	Leak localisation and structure inspection				
				Interaction with an underwater structure (manipulation)				
				Combined scenario				
VEHICLE SPECIFICATIONS								
No. of Thrusters	Thrusters Brand	Thrusters Type	Machining used in the process	Materials used	Software used for mechanical design	Onboard Computer	Software	Wireless Comms
Sensory payload	Does the AUV include BMS?	Please, specify Sonar (if any)	Model of the Sonar	Please, specify which IMU (if any)	Model of the IMU	Connectors	Other electronics	AUV value

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Vehicle name		Team name		Team leader					
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